I've finished the code for ideal environment tracking. I've also finished the structure that houses the circuitry and tracking cells. The servos seem to be working fine with the Arduino. I've also found out what possible kits we can use for the larger solar system. We will end up needing a geared servo solution. This may cost a good bit of money, but will most likely be the only option to complete the final system.

Next week I should be getting around to finalizing the non-ideal environment code.