Progress:

- Breedlove has started construction on the main structure (finished Sunday/Mon)
- I've started debugging the non-ideal code
- We built the servos. They didn't not come assembled. There were a few thing the group had to do.
  1. The stopped that did not allow full 180 degree rotation needed to be taken out.
  2. The potentiometer inside the servo had to be taken out and replaced with a new one
  3. Gearbox Servos needed to be tested to ensure proper function

- Began working on the PDR paper and Presentation
- Michael is working on compiling info for the poser. I will be doing the design of it later this week or early next